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**APPLICATION
FOR
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LETTERS PATENT**

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FOR: METHOD AND SYSTEM FOR
RECORDING AND REPLAYING THE
EXECUTION OF DISTRIBUTED JAVA
PROGRAMS

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METHOD AND SYSTEM FOR RECORDING AND REPLAYING THE EXECUTION OF DISTRIBUTED JAVA PROGRAMS

CROSS-REFERENCE TO RELATED APPLICATIONS

5 The present application is related to U.S. Patent Application No. 08/956,717, filed on October 23, 1997, to Choi et al., entitled "DETERMINISTIC REPLAY OF MULTITHREADED APPLICATIONS" having IBM Docket No. YO997-355, and to U.S. Patent Application No. 09/____, filed on _____, to Choi et al., entitled "DETERMINISTIC REPLAY OF JAVA MULTITHREADED PROGRAMS ON MULTIPROCESSORS" having IBM Docket No. YO999-501, both assigned to the present assignee, and incorporated herein by reference.

BACKGROUND OF THE INVENTION

Field of the Invention

15 The present invention relates to computer processing systems, and more particularly to tools, techniques and processes, such as debugging tools and visualization tools, for recording and replaying the execution of distributed programs on such computer processing systems.

Description of the Related Art

Distributed programming is a form of information processing in which work is performed by separate computers linked through a communication network.

Typically, a complex set of software services and hardware services that implement a standardized set of communication protocols, such as transfer control protocol (TCP)/Internet Protocol (IP), is used to communicate information over the communication network. A more detailed description of exemplary communication protocols used in today's communication networks can be found in Tanenbaum, "Computer Networks," Prentice-Hall, Inc., Third Edition, 1996, herein incorporated by reference in its entirety.

The JAVA™ programming language reduces many of the complexities of distributed programming by providing many programmer-friendly features including language-level support for multiple threads of execution within a single program.

Further, standard and relatively simple Application Programming Interfaces (APIs) have been provided in JAVA™ for defining a set of interfaces to the complex set of software services and hardware services used in communicating information over today's communication network. The core communication APIs in Java™ are centered around communication end points called "sockets". The concepts exported and options supported by the Java™ Socket API are essentially a set of higher level abstractions and operations that can be mapped on a simple blocking subset of a low-level, but more powerful, socket-based interfaces offered by operating systems such as UNIX®, the Microsoft Windows®, and the Microsoft NT® operating systems.

In JAVA Socket API, three types of sockets are supported: 1) a point-to-point stream socket that supports reliable, streaming delivery of bytes; 2) a point-to-point datagram or packet-based socket on which message packets can be lost or received out of order; and 3) a multicast (e.g., point-to-multiple-points) socket on which a datagram may be sent to multiple destination sockets. For more details, see “Java Language Specification”, J Gosling, B. Joy and G. Steele, Addison Wesley and “Java 1.1 Developer’s Handbook”, P. Heller, S. Roberts, with P. Seymour and T. McGinn, Sybex. These features have resulted in the growing use of JAVA for creating application components in JAVA that communicate over the network.

However, the factors of non-determinism introduced by the presence of concurrent threads of execution, operating system scheduling, variable network delays and potentially variable delivery of network messages make the understanding and testing of multi-threaded distributed JAVA application execution a difficult and a laborious process.

Moreover, repeated execution of a program is common while debugging a program, and non-determinism may result in a “bug” appearing in one execution instance of the program and not appearing in another execution instance of the same program.

Further, the performance behavior can be different from one execution instance of a program to another execution instance of the same program. Given the size and the number of execution sequences possible in the completion of these distributed programs, it is an extremely difficult task for a programmer to solve correctness and performance problems since it is difficult to reproduce an execution instance.

For example, as mentioned above, replay is a widely accepted technique for debugging deterministic sequential applications. Replay for debugging, however, fails to work for

non-deterministic applications, such as distributed and multithreaded Java applications.

BUGNET's handling of non-deterministic message sent and received by processes is similar to the handling of User Datagram Protocol (UDP) datagrams (e.g., see R. Curtis and L. Wittie, "BUGNET: A debugging system for parallel programming environments", Proceedings of the 3rd IEEE International Conference on Distributed Computing Systems, pages 394-399, 1982). It logs the received message identifications during the record phase, and consumes the received messages according to the log during the replay phase while buffering yet to be consumed messages. However, it does not address the issue of non-deterministic events due to multithreading within a process that interact with non-deterministic message receives, nor does it address non-deterministic partial receive of messages through "reliable" connections.

Additionally, replay systems based on Instant Replay (e.g., see Thomas J. Leblanc and John M. Mellor-Crummy, "Debugging parallel programs with instant replay", IEEE Transactions on Computers, C-36(4):471-481, April 1987; and J. Sienkiewicz and T. Radhakrishnan. DDB: A distributed debugger based on replay", Proceedings of the IEEE Second International Conference on ICAPP, pages 487-494, June 1996) addresses both non-determinism due to shared variable accesses and messages. Each access of a shared variable, however, is modeled after interprocess communication similar to message exchanges. When the granularity of the communication is very small, such as the case with multithreaded applications, the space and time overhead for logging the interactions becomes prohibitively large. Instant Replay also addresses only atomic network messages like the UDP datagram.

Russinovich and Cogswell's approach (e.g., see Mark Russinovich and Bryce Cogswell, "Replay for concurrent non-deterministic shared memory applications", Proceedings

of ACM SIGPLAN Conference on Programming Languages and Implementation (PLDI) pages 258-266, May 1996) addresses specifically multithreaded applications running only on a uniprocessor system. They modified the Mach operating system to capture the physical thread scheduling information. This makes their approach highly dependent on an operating system.

5 Another scheme for event logging (e.g., see L. J. Levrouw, K. M. R. Audenaert and J. M. Van Campenhout, "Execution replay with compact logs for shared-memory systems," Proceedings of the IFP WG10.3 Working Conference on Applications in Parallel and Distributed Computing, IFIP Transactions A-44, pages 125-134, April 1994) computes consecutive accesses for each object, using one counter for each shared object.

As described in detail below, the unique and unobvious structure and method of the present invention differ from theirs in that the present invention computes a logical thread schedule, using a single global counter. Thus, the inventive scheme is much simpler and more efficient than the conventional techniques on a uniprocessor system.

Further, Netzer et. al. address the issue of how to balance the overhead of logging during the record phase with the replay time (e.g., see R.H.B Netzer, S. Subramanian, and X. Jian, "Critical-path-based message logging for incremental replay of message-passing programs", Proceedings of the 14th IEEE International Conference on Distributed Computing Systems, June 1994). Even for a closed world system (e.g., where all components of the distributed application are being replayed), contents of messages are stored selectively to avoid executing the program

20 from the start. Combined with checkpointing (e.g., see Y. M. Wang and W. K. Fuchs, "Optimistic message logging for independent checkpointing in message-passing systems", Proceedings of IEEE Symposium on Reliable Distributed Systems, pages 147-154, October

YO999-502 (YOR.149)

1992), storing contents of messages allows for bounded-time replay to an arbitrary program points.

Accordingly, it is highly advantageous to have methods for recording and replaying a distributed JAVA application so that programmers can easily reproduce application behavior and focus their efforts towards analyzing and solving the problems in application execution. However, hitherto the present invention, such a method (and system) has not been provided to the programmers/users of computer processing systems.

SUMMARY OF THE INVENTION

In view of the foregoing and other problems, drawbacks, and disadvantages of the conventional systems and methods, an object of the present invention is to provide a method and system for recording and replaying the execution of distributed programs (e.g., distributed JAVA systems).

Another object is to provide a method for supporting the recording and replaying of distributed JAVA programs and is an improvement and follow-on work to U.S. Patent Application No. 08/956, 717 filed on October 23, 1997, entitled "DETERMINISTIC REPLAY OF MULTITHREADED APPLICATIONS" and having IBM Docket No. YO997-355.

In one aspect of the present invention, a method for recording and replaying execution of distributed programs on computer systems in a distributed environment includes identifying an execution order of critical events of a program, generating groups of critical events of the

program, wherein for each group, critical events belonging to the group belong to a common execution thread, and generating for each execution thread a logical thread schedule that identifies a sequence of the groups so as to allow deterministically replaying of a non-deterministic arrival of stream socket connection requests, a non-deterministic number of bytes received during message reads, and a non-deterministic binding of stream sockets to local ports.

In another aspect of the present invention, a method for supporting execution replay with respect to a datagram socket API includes the support for out-of-order delivery of packets, and non-deterministic number of packets delivered during different executions of the same program.

In yet another aspect of the present invention, a method for supporting execution replay with respect to a multicast socket API includes the support for datagrams (packets) being sent to multiple receivers.

These methods may be used by interactive tools such as program debuggers and visualizers to replay specific execution instances of a distributed JAVA application for purposes such as program understanding, visualization and debugging.

With the method and system of the invention, recording and replaying a distributed JAVA application are provided so that programmers can easily reproduce application behavior and focus their efforts towards analyzing and solving the problems in application execution.

Further, the invention provides repeating the exact behavior of thread execution and events in a distributed environment, as opposed to earlier work by the inventors in which behavior was logged only for events of accessing shared variables or synchronizations among threads running on a single machine.

In the conventional systems, there are applications running on Java virtual machines, but there is no mechanism for deterministically replaying the JAVA applications and their threads. With the invention, there is a mechanism for deterministically replaying events in which the JAVA virtual machine is modified to record events. To enable this process, the JAVA virtual machines communicate with one another, and events are recorded on each virtual machine.

Further, while the co-pending application mentioned above guarantees the same order of messages sent, the present invention records an arrival ordering which guarantees the same order of messages received by each thread, and, thereby, the replay of applications. Indeed, the present invention extends the capabilities of the earlier invention to network-related communication by making sure that messages are received by each thread during the replay mode in the same order as they are received during the record mode.

Hence, when JAVA application programs are running on two or more different microprocessors (e.g., JAVA Virtual Machines) in a networked environment, the invention provides a method and system for achieving a deterministic replay under such a scenario.

The invention provides such a capability by changing (modifying) the implementation of the virtual machines to record what transactions are occurring at the application level and uses this information the next time around to replicate the same behavior. Thus, the application itself is not being changed, but only the implementation of the virtual machines.

Hence, in contrast to the related work which addressed only the issue of a plurality of threads which were running on a single virtual machine and capturing a data set to execute replay, the present invention is directed to a plurality of (e.g., two) virtual machines having

applications on each machine and having threads of a same JAVA application program running, and recording events to provide a deterministic replay of events on all these virtual machines.

Thus, for example, given three components of a distributed application (component1, component2 and component3) running on virtual machines VM1, VM2 and VM3 respectively and communicating via sockets, the invention provides deterministic replay such that the correct messages are delivered to each component (component1, component2 and component3) of the said distributed application. Hence, while the related work guarantees the sending order, the present invention records the arrival ordering, and guarantees order and replay of the specific applications.

Such is achieved by the plurality of machines recording events at each machine, and each machine communicating with one another, and thus the order of the replay of the application on multiple virtual machines can be guaranteed.

BRIEF DESCRIPTION OF THE DRAWINGS

The foregoing and other objects, aspects and advantages will be better understood from the following detailed description of a preferred embodiment of the invention with reference to the drawings, in which:

Figure 1 illustrates an exemplary computer processing system on which the present invention may be implemented;

Figures 2(a)-2(d) illustrates exemplary physical thread schedules for an exemplary program;

Figure 3A illustrates a flow chart of the software tool of the invention for capturing a logical thread schedule;

5 Figure 3B illustrates a general critical section (~~GC-critical section~~) for general critical events;

Figure 4 illustrates exemplary logical thread schedules and how they are identified;

Figure 5A illustrates a state diagram that illustrates the operation of the software tool of the present invention in replay mode and specifically a replay finite state automation;

Figure 6 illustrates a server and three clients showing connections during first and second executions, and specifically a network-delays problem;

Figure 7 illustrates a server and three clients, and specifically a mechanism for deterministic replay of connections;

Figures 8(a) and 8(b) respectively illustrate a flowchart for implementing a record and replay for a read;

Figures 9(a) and 9(b) respectively illustrate a flowchart for implementing a record and replay code for a write.

Figure 10 illustrates an "accept-and-connect" process in a record mode for a client and server configuration;

20 Figure 11 illustrates an "accept process" in replay mode for a server;

Figures 12(a) and 12(b) respectively illustrate an exemplary flowchart for implementing a more efficient record and replay code of a read and a record and replay code for a write, and

Figure 13 illustrates a programmable storage medium 1300 for storing a program of the method according to the present invention.

DETAILED DESCRIPTION OF PREFERRED EMBODIMENTS OF THE PRESENT INVENTION

Referring to Figure 1, there is shown a block diagram of a computer system 100 on which a preferred embodiment of the present invention operates.

The computer system 100 includes one or more application programs 102 and an operating system 108 that operate on a computer platform 104. The platform 104 includes a hardware unit 112 that includes one or more central processing units (CPUs) 116 (which are typically referred to as CPUs/processors), a random access memory (RAM) 114, and an input/output interface 118.

Various peripheral components may be connected to the computer platform 104 including a terminal 126, a data storage device 130, and a printing device 134. The operating system 108 coordinates the operation of the various components of the computer system 100. An example of computer system 100 is the IBM RISC System/6000 (RISC System/6000® is a trademark of the IBM Corporation.) It is readily understood that those skilled in the computer arts will be familiar with many equivalent computer systems 100.

The operating system 108 of the present invention provides multi-threading capabilities wherein multiple concurrent threads of control are dispatched within a single shared address

space. Examples include the built-in thread support of operating systems supporting the Java™ Virtual Machine, Microsoft's Windows NT® operating system, and the POSIX threads package that is available on many operating systems, for instance as the pthreads package of IBM's AIX® operating system.

5 According to the present invention, a software tool and method are provided that operate as an application program 102 on the computer platform of FIG. 1. The software tool provides the deterministic replay of a non-deterministic execution instance of a program. The software tool operates in two modes:

- in a record mode, the tool records the logical thread schedule information of the execution while the program runs; and
- in a replay mode, the tool reproduces the execution behavior of the program by enforcing the recorded logical thread schedule information.

Replaying a multithreaded program involves capturing the thread schedule information during one execution of the program and reproducing the exact same schedule while replaying the execution. A thread schedule of a program is essentially a sequence of time intervals (e.g., time slices). Each interval in this sequence corresponds to the execution of a single thread. Thus, interval boundaries correspond to thread switch points. The thread schedule information obtained from a thread scheduler is referred to as a “physical thread schedule information”, and each time interval in a physical thread schedule is referred to as a “physical schedule interval”.

As mentioned above, the relative simplicity of the Java programming language and its platform API has made Java attractive as an application development platform. However, certain features of Java, such as multiple threads and network events introduce non-determinism in an application's execution behavior. Non-deterministic execution behavior leads to difficulties in program understanding and debugging. For example, as mentioned above, repeated execution of a program is common while debugging a program. However, non-determinism may result in a bug appearing in one execution instance of the program and not appearing in another execution instance of the same program. Further, the performance can be different from one execution of a program to another execution of the same program.

Providing deterministic replay of application execution is a key step towards programmer productivity and program understanding (e.g., see Anne Dinning and Edith Schonberg, "An empirical comparison of monitoring algorithms for access anomaly detection", Second ACM SIGPLAN Symposium on Principles and Practice of Parallel Programming, pages 1-10, Seattle, Washington, March 1990. ACM Press; Thomas J. Leblanc and John M. Mellor-Crummey. "Debugging parallel programs with instant replay", IEEE Transactions on Computers, C-36(4):471-481, April 1987; and Mark Russinovich and Bryce Cogswell, "Replay for concurrent non-deterministic shared memory applications", Proceedings of ACM SIGPLAN Conference on Programming Languages and Implementation (PLDI), pages 258-266, May 1996). Towards this goal, the present inventors developed a replay framework based on logical thread schedules and logical intervals.

An application of this framework was previously developed in the context of a system called "DejaVu" (e.g., proprietary to IBM Corporation) that provides deterministic replay of

multi-threaded Java programs on a single Java Virtual Machine(JVM) (e.g., see Jong-Deok Choi and Harini Srinivasan, "Deterministic replay of java multithreaded applications", Proceedings of the ACM SIGMETRICS Symposium on Parallel and Distributed Tools, pages 48-59, August 1998.). In contrast, the present invention describes deterministic replay for distributed Java applications running on multiple JVMs.

The inventive techniques for handling distributed events seamlessly integrate with the earlier work on replay for multi-threaded applications on a single JVM (e.g., see U.S. Patent Application No. 08/956,717 having IBM Docket No. YO997-355). The result of the integration is an efficient deterministic replay tool for multithreaded and distributed Java applications. Such replay techniques may be implemented for distributed Java applications as extensions to a Java Virtual Machine (JVM), the run-time system on which a Java application will execute. The extended JVM will be referred to hereinafter as "DJVM."

Three major cases are to be considered for a distributed Java application, including, in terms of how much control the distributed system can have over an application: (1) a closed world case, where all the JVMs running the application are DJVMs; (2) an open world case, where only one of the JVMs running the application is a DJVM; and (3) a mixed world case, where some, but not all the JVMs running the application are DJVMs.

For a distributed Java application, DJVM needs to replay execution behavior as defined by Java network communication API. At the core, this API is centered around communication end points called "sockets". Three socket types are supported: 1) a point-to-point stream or TCP socket that supports reliable, streaming delivery of bytes; 2) a point-to-point datagram or packet-based User Datagram Protocol (UDP) socket on which message packets can be lost or received

out of order; and 3) a multicast (point-to-multiple-points) socket on which a datagram may be sent to multiple destination sockets. With respect to replay, multicast sockets are just a special case of UDP sockets. Behaviors of TCP and UDP sockets differ and therefore need different solutions for execution replay.

5 A DJVM runs in two modes: (1) a record mode, wherein, the tool records the logical thread schedule information and the network interaction information of the execution while the Java program runs; and (2) a replay mode, wherein, the tool reproduces the execution behavior of the program by enforcing the recorded logical thread schedule and the network interactions. DJVM uses a portable approach that is independent of the underlying thread scheduler and is believed to be the first tool that completely addresses the issues in handling all the non-deterministic operations in the context of deterministic replay of distributed and multithreaded Java applications. It is noted that the approach is general and can be applied to distributed and multithreaded applications written in a language with features similar to Java.

 Herein below are described, in order, the replay framework and methodology and the application of these concepts for multithreaded Java applications (e.g., more detailed description can be found in the above-mentioned article by Jong-Deok Choi and Harini Srinivasan, "Deterministic replay of Java multithreaded applications", Proceedings of the ACM SIGMETRICS Symposium on Parallel and Distributed Tools, pages 48-59, August, 1998), the context for describing distributed replay by providing a general idea on how the framework can be applied for replaying network activity, the replay techniques for closed worlds for TCP and UDP sockets, the techniques for TCP and UDP sockets for open and mixed world cases, and a comparison of the inventive approach to previous approaches.

Replay Framework

Replaying a multithreaded program on a uniprocessor system can be achieved by first capturing the thread schedule information during one execution of the program, and then enforcing the exact same schedule when replaying the execution (e.g., see Mark Russinovich and Bryce Cogswell, “Replay for concurrent non-deterministic shared memory applications”, Proceedings of ACM SIGPLAN Conference on Programming Languages and Implementation (PLDI), pages 258-266, May 1996). For purposes of this application, a “uniprocessor” is defined as a computer system with a single central processing unit on which all the user application code is executed.

A thread schedule of a program is a sequence of time intervals (time slices). Each interval in this sequence contains execution events of a single thread. Thus, interval boundaries correspond to thread switch points.

The thread schedule information obtained from a thread scheduler is referred to as the “physical thread schedule information”, and each time interval in a physical thread schedule is referred to as a “physical schedule interval”. Capturing the physical thread schedule information is not always possible, in particular, with commercial operating systems. Rather than relying on the underlying physical thread scheduler (e.g., either an operating system or a user-level thread scheduler) for physical thread scheduling information, the logical thread schedule information, that can be computed without any help from the thread scheduler, is captured.

To better understand the notion of logical thread schedule, consider a simple multithreaded Java™ program below:

```

class Test {

    static public volatile int f = 0; // shared variable
    static public volatile int g = 20; // shared variable

    static public void main(String argv[]) {
        int j; // local variable
        MyThread t1 = new MyThread();
        t1.start();
        j = 20;
        System.out.println("f = " + f + " j = " + j);
    }
}

class MyThread extends Thread {
    public void run() {
        int k; // local variable
        k = 5;
        Test.f = Test.f + k;
        Test.g = Test.g - k;
    }
}

```

Here, thread main starts a child thread, *t1*. Both main and *t1* can access the (shared) member variables, *f* and *g* (e.g., main reads *f* and *t1* reads and writes variables *f* and *g*). Variables *k* and *j* are thread-local variables, while *f* and *g* are thread-shared variables. Declaring the shared variables volatile forces each thread not to treat them as thread-local variables in the absence of any explicit synchronization operations. The term “variable” denotes the unique memory location associated with the variable at an execution point.

Figures 2(a) and 2(b) depicts some execution instances (e.g., physical thread schedules) of the example program on a uniprocessor machine. It is noted that time is marked in the vertical direction. The only difference between the execution instances as shown in Figures 2(a) and 2(b)

is the time when variable j is updated. This does not affect the execution behavior of the program because accessing a local variable is a local event of a thread.

That is, in Figure 2(a), the shared variable foo is incremented by $t1$ before the thread main can print the value of foo . Hence, for this execution, the value printed is 5. The difference between the execution instance in Figures 2(a) and 2(b) is that in the latter case, variable j is updated before thread $t1$ starts executing. The value of foo that gets printed is 0.

The value of f printed by thread main is still 5. However, in both execution instances (e.g., Figures 2(c) and 2(d)), main prints the value 0 of f before $t1$ updates it. Hence, the value printed is 0. Likewise, the value of foo that gets printed is 0. Again, the only difference between the thread schedules 2(c) and 2(d) lies in the order of local variable accesses. That is, in Figure 2(c), k is updated before the saved variable foo is accessed by thread main and in Figure 2(d) k is updated after foo is accessed in main.

Thus, an execution behavior of a thread schedule can be different from that of another thread schedule, if the order of shared variable accesses is different in the two thread schedules. Hence, it is possible to classify physical thread schedules with the same order of shared variable accesses into equivalence classes. In the above example, schedules of Figures 2(a) and 2(b) belong to the same equivalence class. Likewise, schedules of Figures 2(c) and 2(d) belong to one equivalence class. All of the physical thread schedules in an equivalence class are referred to as “a logical thread schedule”.

Synchronization events can potentially affect the order of shared variable accesses, and thus affect the possible logical thread schedules. Examples of such synchronization operations in

Java™ are synchronized methods/blocks and wait. For example, a Java™ Virtual Machine provides several different kinds of synchronization:

5 - **monitorenter**, **monitorexit** are instructions that mark the beginning and end respectively of a critical section. The semantics of a critical section is that only one thread can execute the section of code at any given time. A different thread can enter the critical section only after the first has executed the **monitorexit** operation. However, threads compete to enter a critical section, and during different execution instances, threads may acquire access to the critical section in different orders. Synchronized methods and blocks can be implemented using the **monitorenter** and **monitorexit** instructions.

15 - **wait**, **notify**, **notifyAll** are instructions that can be used to coordinate the execution order of multiple threads. A thread that has executed a **wait** operation on an object must wait to be notified by a different thread executing a **notify** operation on the same object. The thread that executes the **notify** operation on an object wakes up an arbitrary thread waiting on the same object. The **notifyAll** operation can be used to wake up all the corresponding waiting threads.

- **suspend** and **resume** are instructions used to coordinate the execution order. A thread can execute a **suspend** operation that suspends the execution of another

thread or itself. The suspended threads must be explicitly resumed by another thread executing the **resume** operation.

- Finally, it is possible for a thread to execute an **interrupt** operation that interrupts the execution of a thread at any point.

5 All of the above-mentioned synchronization operations affect the execution order of threads, which in turn can affect the order of shared variable accesses and hence the physical thread schedules.

The events, such as shared variable accesses and synchronization events, whose execution order can affect the execution behavior of the application, are referred to as “critical events”. A logical thread schedule is a sequence of intervals of critical events, wherein each interval corresponds to the critical and non-critical events executing consecutively in a specific thread.

In addition, the interactions between synchronization operations in the user application are themselves part of the application and have to be reproduced for the user to correctly understand their program behavior. It is therefore important, in a record/replay tool, to capture all of these synchronization events and the shared variable accesses in order to reproduce the exact same execution behavior of the program. Synchronization events and shared variable accesses of a thread are collectively referred to below as “critical events”.

It is possible to classify physical thread schedules with the same execution behavior into equivalence classes. More specifically, let $s1$ and $s2$ be two physical thread schedules for the same program execution with the same inputs. Let $t1, t2, \dots, tn$ be threads executing in schedules

s1 and *s2*. Schedules *s1* and *s2* are equivalent if the critical events and their order are the same in *s1* and *s2*. In the example presented above, the schedules shown in Figures 2(a) and 2(b) belong to the same equivalence class. Likewise, the schedules shown in Figures 2(c) and 2(d) belong to one equivalence class.

5 The software tool of the present invention preferably refers to all the physical thread schedules belonging to an equivalence class as a logical thread schedule. Thus, if physical schedules *s1* and *s2* are equivalent, they correspond to the same logical thread schedule. More specifically, a logical thread schedule is a sequence of intervals of critical events, wherein each interval corresponds to the critical events executing in a specific thread. Preferably, a given interval satisfies the following properties:

1. all critical events of the interval belong to the same thread;
2. all critical events of the interval are consecutive;
3. only non-critical events can occur between consecutive critical events in the interval;
in other words, given any two critical events *c1* and *c2* of an interval, all critical events of the thread between *c1* and *c2* also belong to this interval; and
4. no two adjacent intervals belong to the same thread.

It is noted that it is not necessary to trace each critical event individually. More specifically, for a particular logical schedule, if multiple critical events always occur in succession and are not separated by a thread switch, then it suffices to trace the critical event interval (e.g., the first critical event and the last critical event). Tracing the critical event interval

rather than every critical event reduces the space requirements for the traces, and consequently improves the performance of the replay tool.

For example, in Figures 2(a)-2(d), in both the logical schedules, the shared variables *foo* and *bar* are accessed in thread *t1*, uninterrupted by thread switches, in the order *foo*; *bar*; *foo*.

5 Rather than trace each of these critical events, the first access to *foo* and the last access to *foo* in *t1* can be traced. Before proceeding to discussing record and replay of critical events, formalizing the notion of logical thread schedule and how such schedules can be captured will be described.

The data representing the logical thread schedule of a program execution preferably includes a set of thread-specific logical schedules each corresponding to a thread created during the execution as follows:

$$\begin{aligned} \text{logical_thread_schedule_for_execution} = \\ & \{ \text{thread_specific_logical_schedule}[1], \dots, \\ & \text{thread_specific_logical_schedule}[i], \dots, \\ & \text{thread_specific_logical_schedule}[\text{number_of_threads}] \}. \end{aligned}$$

15 The thread-specific logical schedule of a thread includes a list of logical schedule intervals (LSIs) each corresponding to an interval during which the specific thread is scheduled for execution as follows:

$$\text{thread_specific_logical_schedule}[i] = \{ \text{LSI}[0], \dots, \text{LSI}[j], \dots, \text{LSI}[\text{last}-1] \}$$

The list is preferably implemented as a linked list during the record phase, when the number of logical schedule intervals is not known *a priori*. It is preferably implemented as an array during the replay phase, when the number is known *a priori*.

5 The logical schedule interval corresponding to an interval i when the specific thread is scheduled for execution, denoted $LSI[i]$, identifies the critical event(s) that occur in the given interval i . Preferably, $LSI[i]$ is an ordered pair $\langle FirstCriticalEvent[i], LastCriticalEvent[i] \rangle$ wherein $FirstCriticalEvent[i]$ identifies the first critical event in the interval i and $LastCriticalEvent[i]$ identifies the last critical event in the interval i . Preferably, the value of $FirstCriticalEvent[i]$ and $LastCriticalEvent[i]$ represent a global clock value that indicates the time that the corresponding event was executed. Such global clock values identify the ordering of events in the execution stream.

10 The logical thread schedule of the present invention as described above preferably is generated using a global counter and a local counter. An example of the operations in capturing the logical thread schedule is illustrated in FIG. 3A.

15 Logical Thread Schedule Intervals

The logical thread schedule of an execution instance on a uniprocessor system is an ordered set of critical event intervals, called "logical schedule intervals". Each logical schedule interval, LSI_i , is a set of maximally consecutive critical events of a thread, and can be represented by its first and last critical events as: $LSI_i = \langle FirstCEvent_i; LastCEvent_i \rangle$.

20 The approach to capturing logical thread schedule information is based on a global counter (i.e., time stamp) shared by all the threads and one local counter exclusively accessed by

each thread (e.g., one local counter being provided for each thread). The global counter ticks (e.g., increments) at each execution of a critical event to uniquely identify each critical event. Therefore, *FirstCEventi* and *LastCEventi* can be represented by their corresponding global counter values. It is noted that the global counter is global within a particular DJVM, not across the network (over multiple DJVMs). Thus, each DJVM includes a different global counter. A local counter also ticks at each execution of a critical event. The difference between the global counter and a thread's local counter is used to identify the logical schedule interval on-the-fly.

The general idea of identifying and logging schedule interval information, and not logging the exhaustive information on each critical event is important for the efficiency of the inventive replay mechanism. In the log file generated by the system, the present inventors have found it typical for a schedule interval to include thousands of critical events, all of which can be efficiently encoded by two, not thousands of counter values.

There are many programs and methods for generating a logical thread schedule including that shown in Figure 3A. It is note that the "global clock" and "global counter" are synonymous.

That is, an example of the operations in capturing the logical thread schedule is illustrated in FIG. 3. The operations begin in step 301 by initializing the variable GLOBAL_CLOCK to 0.

GLOBAL_CLOCK is shared by all threads generated by the physical thread scheduler during the execution of the program. Such threads are denoted as thread[1] through thread[last]. The physical thread scheduler creates such threads in a serial fashion. The software tool of the present invention deterministically assigns a thread identifier to the newly created thread and passes the thread identifier to the newly created thread. The thread identifier is initialized to 0 and incremented automatically for each thread created. For each thread, a thread-specific logical

thread schedule is computed (steps 303 through 315). The figure shows the steps for thread[i] in detail as a representative case.

In step 303, a variable localClock is initialized to 0 and the first logical schedule interval of the thread is created with the initial GLOBAL_CLOCK (0) as its first critical event. Steps 305-315 form a loop that terminates when the thread terminates. For each instruction to be executed in the thread (i.e., the next event), in step 305 it is determined whether the instruction is a critical event. If not, control branches to step 306 wherein the instruction is executed and the operation continues to step 315. Upon execution of the instruction, the processing system identifies the next instruction in the execution sequence. If in step 305 it is determined that the instruction is a critical event, then operation continues to step 307 wherein an atomic operation is performed that executes the critical event, makes a copy GLOBAL_CLOCK_COPY of the current value of GLOBAL_CLOCK and updates GLOBAL_CLOCK. An example of the atomic operation is described below with respect to Figure 5. In this example, the GCCriticalSection represents such atomic operation. Upon execution of the instruction, the processing system identifies the next instruction in the execution sequence. After step 307, operation continues to step 309.

In step 309, it is determined whether there is a gap between GLOBAL_CLOCK_COPY and localClock. The value of GLOBAL_CLOCK, which is reflected in GLOBAL_CLOCK_COPY, can be updated by all the threads; yet localClock can only be updated by the thread that owns it. Therefore, localClock cannot be greater than GLOBAL_CLOCK_COPY. If localClock is equal to GLOBAL_CLOCK_COPY, a thread switch has not occurred between the last event and the current event, and the operation

continues to step 313. If localClock is less than GLOBAL_CLOCK_COPY, a thread switch has occurred between the last event and the current event, and the operation continues to step 311 wherein the current logical schedule interval LSI[i] is completed with the value (localClock-1) as its LastCriticalEvent[i], the counter i is incremented, and a new logical schedule is created with GLOBAL_CLOCK_COPY as its FirstCriticalEvent[i]. In step 311, all threads other than the main thread have an initial interval <0, -1>, which is ignored.

After step 311, the operation continues to step 313 wherein GLOBAL_CLOCK_COPY is incremented and localClock is updated to the incremented value of GLOBAL_CLOCK_COPY. In step 315, it is determined if the current event is the last event of the thread. If not, the operation returns to step 305 and steps 305 to 315 are repeated. If so, the operation continues to step 316 wherein the last logical schedule interval LSI[i] of the terminating thread is completed with the value GLOBAL_CLOCK_COPY as its LastCriticalEvent[i].

Finally, after all the threads have terminated, in step 317, the logical thread schedule information for all the threads is saved in a file.

Figure 4 illustrates logical schedule intervals for an exemplary program execution. Figure 4 shows the execution of four threads (e.g., with time going down along the vertical lines) and local and global counter updates at shared variable accesses in each of the threads.

Identifying and Replaying Logical Schedule Intervals

Referring to Figure 5, which illustrates a replay finite state automation process and the process of identifying and replaying logical schedule intervals, will be described.

Thus, each critical event is uniquely associated with a global counter value. Global counter values in turn determine the order of critical events. Therefore, updating the global counter for a critical event and executing the critical event, are performed in one atomic operation for shared-variable accesses. Some synchronization events are handled differently to avoid deadlocks (e.g., for a detailed description, see the above-mentioned Jong-Deok Choi and Harini Srinivasan, "Deterministic replay of java multithreaded applications", Proceedings of the ACM SIGMETRICS Symposium on Parallel and Distributed Tools, pages 48-59, August, 1998), the present inventors have implemented light-weight GC-critical section (e.g., Global Counter critical section) codes to implement a single atomic action of critical events by guarding them with *GcEnterCriticalSection* and *GcLeaveCriticalSection*, as shown in Figure 3B. It is used when the critical event is a general event (e.g., a shared variable access). *GcEnterCriticalSection* and *GcLeaveCriticalSection* are implemented by acquiring and releasing a light-weight lock (e.g., an "efficient," lock, which does not incur much runtime overhead) called *GCounter_Lock*. Synchronization events with blocking semantics, such as **monitorenter** and **wait**, can cause deadlocks if they cannot proceed in a GC-critical section. Therefore, the invention handles these events differently by executing them outside a GC-critical section (e.g., for a detailed description, see the above-mentioned Jong-Deok Choi and Harini Srinivasan, "Deterministic replay of java multithreaded applications", Proceedings of the ACM SIGMETRICS Symposium on Parallel and Distributed Tools, pages 48-59, August, 1998).

Updating the global counter and executing the event both in one single atomic operation is only needed during the record phase (e.g., as shown in Fig 3(B)). For a thread to execute a schedule interval $LSI\ i = \langle FirstCEventi ; LastCEventi \rangle$, during the replay phase, the thread

waits until the global counter value becomes the same as *FirstCEventi* without executing any critical events. When the global counter value equals *FirstCEventi*, the thread executes each critical event and also increments the global counter value until the value becomes the same as *LastCEventi*.

5 When the global counter value equals *LastCEventi*, the thread fetches its next schedule interval, $LSI\ i+1 = \langle FirstCEventi+1 ; LastCEventi+1 \rangle$, from the log and waits until the global counter value becomes the same as *FirstCEventi+1*. Then, it repeats the above process until it has no more schedule intervals in the log. Figure 5 shows the automaton that each thread executes to reproduce the same execution behavior.

Distributed DJVM

Hereinbelow is described a general idea of how the framework can be applied to DJVM in an extensible manner to handle both multi-threaded and distributed Java applications. in closed, open and mixed world environments.

15 In each of these environments, Deterministic replay of the distributed Java application is ensured by identifying network events as “critical events” (e.g., details for each network event are described below). These network events can potentially change the observable execution behavior of the distributed Java application.

20 Execution order of critical events up to the first network event will be preserved by the DJVM even without the support for network events. The support in DJVM for network events ensures that the network events happen in the same execution order as in the record mode. With network support in DJVM, it can be concluded by induction that DJVM can deterministically

YO999-502 (YOR.149)

replay all critical events, network or non-network. Hereinbelow is described the different solutions in DJVM for replay of network events.

The “closed world” case is by far the more complex case. The replay techniques for TCP and UDP sockets in this world is described immediately below. Then, an overview is provided as to how replay can be supported for both stream and datagram sockets in open and mixed worlds.

Closed World Case

Replay for TCP sockets is described first, followed by that for UDP sockets.

First, regarding supporting stream sockets, the Java APIs (e.g., see Patrick Chan and Rosanna Lee, “The Java Class Libraries, An Annotated Reference”, Addison Wesley Publication, 1997) for stream sockets will be described followed by issues in replaying distributed applications that use stream sockets, and the inventive techniques for recording and replaying for deterministic replay.

Stream sockets are created by *Socket* and *ServerSocket* classes in Java. A client constructs a *Socket* object to connect to a server. In the process of executing the *Socket()* constructor, the client will execute the *connect()* call. The construction is blocked until a connection is established by a server. A server constructs a *ServerSocket* object to specify the port to listen on. It then invokes the *accept()* method of the object to accept a connection request. The *accept()* blocks until a connection is established. It then creates and returns a *Socket* object. The server can close the socket connection via *close()* method of the *ServerSocket* object.

Once a socket is created, *getInputStream()* and *getOutputStream()* of the Socket object return InputStream and OutputStream objects to be used for reading (via *read()* method call) and writing (via *write()* method call) stream data over the socket stream.

Other socket APIs include a method to listen for connections on a stream socket (*listen()*), method to bind a socket to a local port (*bind()*), and a method to determine the number of bytes that can be read without blocking (*available()*).

There are several key issues which must be considered in deterministic replay of stream socket events. Each stream socket call (e.g., *accept*, *bind*, *create*, *listen*, *connect*, *close*, *available*, *read*, *write*) is mapped into a native method call (i.e., a call to a non-Java method, possibly an operating system call) in a JVM implementation. Each of these native calls is referred to as “a network event”. For convenience, hereinbelow, the names of the Java calls for the corresponding native calls will be used when referring to the critical events. For replaying stream socket network events, the following issues are relevant.

Variable network delays: Since network delays can vary for different executions of the same distributed Java application, socket connections can be non-deterministic. Therefore, the first step for deterministic replay of network events is deterministic re-establishment of socket connections among threads. The relevant socket calls that are affected by this issue are *accept()* and *connect()*.

Figure 6 illustrates the above issue with an example. The server application in Figure 6 has three threads *t1*, *t2*, *t3* waiting to accept connections from clients (e.g., this would be a typical scenario in distributed Java applications). Client1, Client2 and Client3 execute the

connect() call, making connection requests to the server. The solid and dashed arrows indicate the connections between the server threads and the clients during two different executions of the distributed Java application.

Variable message sizes: The stream-oriented nature of the connections can result in variable length messages read by the receiver of the messages. In other words, the *read()* method calls can return less than or equal to the number of bytes requested. A simple re-execution of the *read()* method during the replay phase can result in a different number of bytes being read than the number read in the record phase.

Network queries: Operations related to the status and attributes of a connection need to be replayed. For instance, if the particular port number was allocated to a socket during the record phase, the application should see the same port number during the replay phase. The relevant socket calls affected by this issue are *available()* and *bind()*.

Blocking calls: Socket calls such as *accept()*, *connect()*, *read()*, and *available()* are blocking calls. Hence, if these calls are placed within the *GC-critical section*, they can cause the entire DJVM to be blocked until the call completes, and can result in deadlocks and inefficient and heavily perturbed execution behavior.

The invention also provides a record and replay mechanism for stream sockets. That is, each DJVM is assigned a unique JVM identity (DJVM-id) during the record phase. This identity

is logged in the record phase and reused in the replay phase. The DJVM-id allows identification of the sender of a message or connection request.

A network event on a DJVM is identified by a *networkEventId* defined as the tuple $\langle threadNum, eventNum \rangle$, where *threadNum* is the thread number of the specific thread executing the network event and *eventNum* is a number that identifies the network event within that thread. The *eventNum* is used to order network events within a specific thread.

In addition, the *connectionId* is used to identify a connection request at a connect network event. The *connectionId* is the tuple, $\langle dJVMId, threadNum \rangle$, where *dJVMId* is the identity of the DJVM at which the connect event is being generated, and *threadNum* is the thread number of the client thread generating the connection request.

Since threads are created in the same order in the record and replay phases, the inventive implementation guarantees that a thread has the same *threadNum* value in both the record and replay phases. In addition, since events are sequentially ordered within a thread, the *eventNum* of a particular network event executed by a particular thread is guaranteed to be the same in the record and replay phases.

The inventive techniques for record and replay phases that handle the above-mentioned issues, are described below.

Replaying accept and connect: Since these calls are a source of non-determinism, these are made DJVM critical events. Although this guarantees the execution order within a DJVM, it alone is not sufficient for correctness because of non-determinism introduced by network delays. So additional data regarding the connection is stored at the server DJVM. Further, as mentioned

earlier, these calls are blocking calls and executing these calls within a GC-critical section reduces application parallelism and introduces potential for deadlocks. Therefore, the operating system level network operations are allowed to proceed and then mark the network operations as critical events. This marking strategy allows threads performing operations on different sockets to proceed in parallel with minimal perturbation.

In the record phase, at the connect, DJVM-client sends the socket-connection request to the server, possibly accepted by a peer thread on the server. When the socket connection is finally established, the client thread on DJVM-client sends the *connectionId* for the connect over the established socket as the first data (meta data). Note that the *connectionId* is sent to the server via a low level (native) socket write call and is done before returning from the *Socket()* constructor call. This ensures that the *connectionId* is indeed the first data sent over this connection. Finally, just before the connect call returns, DJVM-client performs the GC-critical section for atomically updating the global counter.

In the replay phase, DJVM-client executes the connect and sends the *connectionId* of the connect to the server as the first meta data, just as in the record phase. Since connect is a critical event, DJVM-client ensures that the connect call returns only when the globalCounter for this critical event is reached.

On the server side, during the record phase, at an accept, the DJVM-server accepts the connection and receives the *connectionId* sent by the client as the first meta data at the corresponding connect. The DJVM-server also logs the information about the connection established into the *NetworkLogFile*. For each successful accept call, the log contains

an entry, called a *ServerSocketEntry*, which is the tuple, $\langle serverId, clientId \rangle$, where *serverId* is the *networkEventId* of the corresponding *accept* event and *clientId* is the *connectionId* sent by the DJVM-client.

Given the information stored in a tuple, it is possible for two different threads to have identical *ServerSocketEntry* tuples in their part of the *NetworkLogFile*. However, this lack of unique entries is not a problem. The core, single DJVM ensures the replay of invocation order (not completion) of accepts across threads since *accept* is a synchronized call. Thus for example, if during record phase, a thread *t1* invoked the *accept* method on a socket before thread *t2*, the thread *t1* will invoke the *accept* method before *t2* during replay. Since the client threads also execute their connects in the original order, the connection gets re-established between the same two threads as during original execution. Further, an exception thrown by a network event in the record phase is logged and re-thrown in the replay phase.

Figure 10 shows the process 1000 (code) executed during the record phases by both the client (e.g., that does the connect) and server (e.g., that does the accept).

That is, on the client side 1000A of Figure 10, a first step 1001 the connection request is sent to the server side 1000B (e.g., step 1002 on server side). Then in step 1003 on the client side, the *ClientID* (*connectionId*) in the form of a tuple, $\langle clientJVMId, ClientThreadNum \rangle$ is sent to the server 1000B.

In step 1004 on the server side, the *ClientID* is received and the server side logs $\langle ServerId, ClientID \rangle$ into the *ServerSocketLog* (step 1006).

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YO999-502 (YOR.149)

Then in step 1103, the connection pool is checked for the *recValue*. If the *recValue* is in the connection pool, then the process exits. If the *recValue* is not in the connection pool, then the process continues to step 1104. In step 1104, a connection request is accepted. Thereafter, in step 1105, the *ClientId* is received by the server.

5 In step 1106, it is determined whether *ClientId* is not equal to the *recValue*. If so (e.g., not equal), then the *ClientId* is saved in the connection pool, and the process loops to step 1104. Conversely if in step 1106 it is determined that the *ClientId* is equal to the *recValue*, then the process goes to step 1107 (which is substantially similar to 1000B described above). Finally, after step 1107, the process exits in step 1108.

10 For the example in Figure 6, suppose the solid arrows indicate the connections established during the record phase. Figure 7 shows the inventive mechanism for deterministically replaying the same connections. *L1*, *L2*, *L3* are the log entries made during the accept events by threads *t1*, *t2*, *t3* respectively during the record phase. *Server1Id*, *Server2Id*, *Server3Id* are the *networkEventId* values when *t1*, *t2*, *t3* respectively execute the accept events.

15 Figure 7 also shows the *connectionIds* sent by each client. For example, the *connectionId* from *Client2* is *Client2Id* = *<Client2VMId; tNum2>*.

20 **Replaying read:** Socket read event is identified as a critical event in a DJVM. Since the number of bytes read via a socket read can vary for different executions, in the record phase, the DJVM executes the read and logs the thread-specific *eventNum* and number of bytes read (*numRecorded*) in the *NetworkLogFile*. Since read is a blocking call, it is not placed

within a GC-critical section. Instead, just before the read call returns, the DJVM marks the read as a critical event. In the replay phase, at the corresponding read event, the DJVM thread retrieves the numRecorded number of bytes from the NetworkLogFile corresponding to the current eventNum. Further, the thread reads only numRecorded bytes even if more
5 bytes are available to read or will block until numRecorded bytes are available to read. Finally, the execution returns from the read call only when the globalCounter for this critical event is reached.

Figure 8(a) shows the process during the record mode for *read()*. In step 1801, the *read* event is executed, returning "n", the number of bytes read which is logged in recordedValue in step 1802. The critical event corresponding to the read is logged in step 1803 and the process exits in step 1804. Step 1803 is essentially 1803A which involves entering the GC critical section, updating the global counter and leaving the GC critical section.

Figure 8(b) shows the process during the replay mode for *read()*. In step 852, the *read* critical event is executed returning the number of bytes read, "n", issuing recordedValue as parameter (indicating the number of bytes that should be read). In step 853, it is determined when $n < \text{recorded value}$. If "YES", the process continues to step 855. If n is equal to the recordedValue (e.g., "NO" in step 853), the process records the read critical event (step 856) and exits (step 857). If n is less than the recordedValue, process goes back to step 852, reading bytes until the recordedValue number of bytes are read. Step 856 is essentially step 856A which
20 involves waiting for the GC value to be that recorded for this read in the record Mode and the updating the global counter.

Replaying write: *write* is a non-blocking call and a critical event. *write* is handled by simply placing it within GC-critical section similar to how we handle critical events corresponding to shared variable updates. Figures 9(a) and 9(b) show the record and replay code respectively for *write()*.

5 In step 901a, the process enters the GC-critical section. In step 902a, in the record mode, the process updates the GC and executes the *write()* event. Finally, step 903a involves exiting the GC critical section.

In the replay mode, step 901b, waits until the global counter value equals the recorded global counter value for this write event. Step 902b executes the *write* event and step 903b updates the global counter.

Since *SocketInputStream.read* and *SocketOutputStream.write* are not synchronized calls, multiple *writes* on the same socket may overlap. If the order of *writes* overlap, the order of critical events is potentially lost. While replaying the *writes* and the corresponding *reads*, we have to ensure that all the *writes* to the same socket happen in the same order and all the *reads* (from the socket) read the bytes in the same order in both the record and replay modes.

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A solution is to just record the occurrence of such an event and allow other unrelated events (i.e., events that do not operate on the same socket) to proceed. Events that do use the same socket will be blocked by using a lock variable for each socket. This is shown in Figures 12(a) and 12(b) respectively. That is, Figures 12(a) and 12(b) respectively illustrate an exemplary flowchart for implementing a more efficient record and replay code of a read and a record and replay code for a write. The *enterFDCriticalSection(socket)* in step 1201 (1251) of figures 12(a) and 12(b) ensures that only *reads* or *writes* corresponding to that socket execute the code inside.

This scheme allows some parallelism in the record and replay modes and also preserves the execution ordering of the different critical events. The additional cost in this scheme is the cost of the extra lock variables per socket and the slightly increased implementation complexity.

Replaying available and bind: The *available* and *bind* events are also treated as critical events. Both these events implement network query. In the case of *available*, it checks the number of bytes available on the stream socket, and *bind* returns the local port to which the socket is bound.

Since *available* is a blocking call, in the record phase, it is executed before the GC-critical section. In addition, the DJVM records the actual number of bytes available. In the replay phase, the *available* event can potentially block until it returns the recorded number of bytes, i.e., until the recorded number of bytes are available on the stream socket.

In the case of *bind*, in the record phase, it is executed within a GC-critical section and the DJVM records its return value. In the replay phase, we execute the *bind* event, passing the recorded local port as argument.

Other stream socket events: The other stream socket events that are marked “critical events” are *create*, *close*, and *listen*, all of which have to be recorded to preserve execution order. These critical events are handled by simply enclosing them within the GC-critical section, similar to how critical events corresponding to shared variable updates, are handled.

Supporting Datagrams Sockets

TCP socket is designed to be reliable. If data is lost or damaged during transmission, TCP ensures that the data is sent again. If data or packets arrive out of order, TCP rearranges them to be in the correct order. User Datagram Protocol (UDP) is an alternative protocol to send data over the network, and is unreliable. The packets, called datagrams, can arrive out of order, duplicated, or some may not arrive at all. It is the JAVA application's responsibility to manage the additional complexity.

For deterministic replay of applications using UDP, DJVM must ensure the same packet delivery behavior during the replay as during the record phase. In other words, the replay mechanism must ensure that the packet duplication, packet loss and packet delivery order in the record phase is preserved in the replay phase. Hereinbelow is described how to achieve this replay for Datagram (UDP) sockets, and how multicast sockets can be easily accommodated by extending the mechanism for Datagram sockets from a point-to-single-point scheme to a point-to-multiple-points scheme.

In Java, there exist Datagram socket APIs, and UDP sockets are created via the *DatagramSocket* class (e.g., see Patrick Chan and Rosanna Lee, "The Java Class Libraries, An Annotated Reference", Addison Wesley Publication, 1997). A *DatagramPacket* object is the datagram to be sent or received through the *DatagramSocket* object via *send()* and *receive()* methods of the *DatagramSocket* object. The *send()* and *receive()* are both blocking calls.

A datagram socket is closed via *close()* method of the socket object. As in the case of stream sockets, each of the datagram socket calls can be implemented in a JVM via a low-level native call. The names of the UDP socket calls are used to refer to the low level native calls (e.g., network events). The UDP *send*, *receive* and *close* events are critical events in DJVM.

The following Java code, called `DatagramClient`, describes a typical example of how a Java client creates a UDP datagram and sends it to the server.

```
100: void DatagramClient(byte[] data, String serverName,  
    int port)  
5  101: {  
    102:     InetAddress sever = InetAddress.getByName(serverName);  
    103:     DatagramSocket dSocket = new DatagramSocket();  
    104:     dPacket = new DatagramPacket(data, data.length, server,  
        Port);  
10  105:     dSocket.send(dPacket);  
    199: }
```

Line 103 creates a new `DatagramSocket`, line 104 creates a new `DatagramPacket`, and line 105 sends the `DatagramPacket` to the `DatagramSocket`.

The following Java code, called `DatagramServer`, describes a typical example of how a Java server receives a UDP datagram.

```
200: void DatagramServer(byte[] data, int port)  
201: {  
202:     DatagramSocket sSocket = new DatagramSocket(port);  
203:     sPacket = new DatagramPacket(data, data.length);  
204:     dSocket.receive(sPacket);  
20  205: }
```

Line 202 creates a new `DatagramSocket`, line 203 creates a new receive-buffer `DatagramPacket`, and line 204 receives incoming `DatagramPacket` and stores it into the `DatagramPacket` created at line 203.

25 For the record phase, the following pseudo code, called *DataGramSendRecord*, corresponds to the implementation of `DatagramSocket.send(DatagramPacket packet)`. An example invocation thereof is shown in line 105 above, for the record phase. `DGNetEventId` is a the pair `<dJVMId, dJVMgc>`, where `dJVMId` is the id of the sender DJVM and `dJVMgc` is the globalcounter at the sender DJVM associated with the *send* event.

```

300: final static int NetworkEventIdLength = 8; // b bytes
301: final static int TagLength = 1;
302: final static byte WHOLE_UDP = 0; // whole udp
303: final static byte FRONT_UDP = 1; // front of a split udp
5 304: final static byte REAR_UDP = 2; // rear of a split udp
305: void DatagramSendRecord(DatagramPacket dp)
306: {
307:     int dpLength = dp.getLength();
308:     DGNetEventId DGnetEventId GenerateNetworkEventId();
10 309:     if ((dpLength + NetworkEventIdLength + TagLength) <=
        MAX_UDP_LENGTH)
310:     { // no need to split
        // just append DGNetEventId and WHOLE_UDP tag
311:         dp = Append(dp, DGNetEventId);
15 312:         send(dp); // real send of the OS
313:     }
314:     else
315:     { // need to split dp into two dp's
316:         DatagramPacket dp2 = SplitRear(dp, DGNetEventId);
20 317:         dp = SplitFront(dp, DGNetEventId);
318:         send(dp); // real send of the OS
319:         send(dp2); // real send of the OS
320:     }
321: }

```

25 During the record phase, the sender DJVM intercepts a UDP datagram sent by the application, called an *application datagram*, and inserts the DGNetEventId of the send event at the end of the data segment of the application datagram. The DJVM also increases the length field of the datagram to include the added size for the datagram id. At line 311, Append(dp, DGNetEventId) appends DGNetEventId and WHOLE_UDP tag at the end of
30 dp. It also increases the length field of the *DatagramPacket* accordingly.

The datagram size, due to appending DGNetEventId (and the tag), can become larger than the maximum size allowed for a UDP datagram (e.g., usually limited by 32K). When this happens, the sender DJVM splits the application datagram into two, which the receiver DJVM combines into one datagram again at the receiver side.

At line 316, `SplitRear(dp, ...)` creates a new `DatagramPacket dp2` from the end of `dp` such that `dp.getLength() - dp2.getLength()` equals `MAX_UDP_LENGTH - (NetworkEventLength + 1)`: it will give enough room at the end of `dp` to append `DGNetEventId` and the one-byte long tag. It will also append `DGNetEventId` and `REAR_UDP` tag to the end of `dp2`, and also increases the length field of `dp2` accordingly.

At line 317, `SplitFront(...)` will insert `DGNetEventId` and `FRONT_UDP` tag at the end of `dp`, and update the length field of `dp` as `MAX_UDP_LENGTH`. The split datagrams carry the same `DGNetEventId`, but different tags, `FRONT_UDP` or `REAR_UDP`, to indicate the portion (e.g., front or rear), it represents so that it can be combined correctly at the receiver. A non-split datagram carries its own tag, `WHOLE_UDP`, that distinguishes it from a split datagram.

Line 308 generates a new `DGNetEventId` by atomically incrementing `gCounter` of the client thread.

The following pseudo code, called `DataGramReceiveRecord`, corresponds to the implementation of `DatagramSocket.receive(DatagramPacket packet)`, an example invocation of which is shown in line 204 above, for the record phase.

```

400: void DatagramReceiveRecord(DatagramPacket dp)
401: {
402:     int rGCounter = GetNewGCounter();
403:     for(;;) { // forever (not really)
404:         receive(dp); // real receive of OS
405:         DGNetEventId dgramId = GetNetworkEventId(dp);
406:         byte tag = GetTag(dp);
407:         if (tag == WHOLE_UDP)
25 408:             { // whole udp received.
409:                 AdjustLength(dp);

```

```

410:         RecordDatagramLog(rGCounter, dgramId);
411:         return; // terminate the loop
412:     }
413:     else if (tag == FRONT_UDP)
5 414:     { // check if the next is REAR_UDP
415:         DatagramPacket dp2 = new DatagramPacket(...);
416:         receive(dp2);
417:         DGNetEventId dId = GetNetworkEventId(dp2);
418:         byte tag = GetTag(dp2);
10 419:         if (tag == WHOLE_UDP)
420:             { // well, we will forget about the FRONT_UDP
                // and just return dp2 as the new dp
421:                 AdjustLength(dp2);
422:                 RecordDatagramLog(rGCounter, dId);
15 423:                 CopyIntoDp(dp, dp2);
424:                 return;
425:             }
426:         else if ((tag == REAR_UDP) && (dgramId == dId))
427:             { // matched one is found; combine into one
428:                 CombinedDatagram(dp, dp2);
429:                 RecordDatagramLog(rGCounter, dgramId);
430:                 return; // terminate the loop
431:             }
432:         // forget about both hdp and dp2, and repeat loop
433:     } // if (tag == FRONT_UDP) ...
434:     else // tag == REAR_UDP
435:     {
436:         ... // similar code between Line 414 and 433
                // except that it will look for matching
                // FRONT_UDP, not REAR_UDP.
427:     }
428: } // for (;;)
429: }

```

The receiver DJVM first checks the tag of the received *DatagramPacket* *dp*. If the tag is WHOLE_UDP (Line 407), it logs the received datagram into a log called *RecordedDatagramLog* (Line 410) and returns with the received *dp* (Line 411). Each entry in the log is a tuple *<ReceiverGCounter ; datagramId>*, where *ReceiverGCounter* is the global counter value at the receive event in the receiver DJVM, *datagramId* is the *DGNetEventId* of the received datagram. *GetNetworkEventId* (Line 405) extracts the *DGNetEventId* from a received

DatagramPacket, and *GetTag* (Line 406) extracts the tag from the received packet. *AdjustLength* (Line 409) decreases the length field of the received packet by the combined length of *DGNetEventId* and the tag.

Multiple datagrams with identical *DGNetEventId* are also recorded during the record phase. It is noted that the same datagram can be delivered more than once during the record phase, all of which must be delivered to the application during record and replay.

If the tag is *FRONT_UDP* (Line 413), the DJVM receives the next packet and check it is the matching *REAR_UDP*. If so (Line 426), it combines the two UDP packets into one packet, and logs the received datagram into the log (Line 428). It then returns (Line 430). If the new packet (e.g., the next packet, is itself a whole UDP (tag is *WHOLE_UDP*), the DJVM discards the first packet, copies the new packet into the first packet (Line 423), and logs the new packet as the received packet. It then returns (Line 424).

If none of the above two cases applies, the DJVM discards both the first and the second packets, and repeats the entire receive loop at Line 403.

If the tag is *REAR_UDP* (Line 434), steps similar to the case of *FRONT_UDP* are taken, but looking for the matching *FRONT_UDP* split packet (Lines 435 through 427).

Regarding the replay phase, for reliable delivery of User Datagram Protocol (UDP) packets during the replay, a reliable UDP mechanism is used that guarantees reliable, but possibly out of order, delivery of intrinsically unreliable UDP datagrams.

If no reliable UDP is available, a pseudo-reliable UDP can be implemented as part of the sender and the receiver DJVMs by storing sent and received datagrams and exchanging

acknowledgment and negative-acknowledgment messages between the DJVMs. It is noted that a datagram delivered during replay can be ignored if it was not delivered during record.

Given a reliable UDP mechanism, deterministic delivery of UDP packets to the application is similar to the mechanism described before for deterministic socket connection (e.g., in the above-mentioned U.S. Patent Application No. 08/956, 717). For UDP delivery, the *DGNetEventId* of each UDP packet is used for uniquely identifying each datagram. A datagram entry that has delivered multiple times during the record phase due to duplication is kept in the buffer until it is delivered to the same number of read requests as in the record phase.

Multicast datagram sockets can be easily supported by extending the support for datagram sockets. The *send* needs to send the same packet(s) to all the target sockets, instead of to only one. The receiver need not be changed.

Open and Mixed World Cases

In the open world case, only one component of the distributed application is running on a DJVM. Network events, in this case, are handled as general input/output (I/O). That is, any input messages are fully recorded including their contents during the record phase. During the replay phase, any network event at the receiver DJVM is performed with the recorded data, not with the real network data.

For example, a *receive datagram socket* event during the replay phase returns a datagram object created from the data recorded during the record phase. During the record phase, a client DJVM requesting a stream socket connection to a non-DJVM server logs the results. During the replay phase, the results of the corresponding connection request are retrieved from the log. The

actual operating system-level connect call is not executed. Likewise, any message sent to a non-DJVM thread during the record phase need not be sent again during the replay phase.

In a mixed-world case, some components of the application are running on DJVM and others on non-DJVM. If the environment is known before the application executes, one could simply fall back on the DJVM scheme for the open-world case. However, with a slightly more machinery, it is possible to optimize on space overheads by using the closed-world scheme for communication with DJVMs and saving additional state during the communication with non-DJVMs.

As shown in Figure 13, in addition to the hardware and process environment described above, a different aspect of the invention includes a computer-implemented method for recording and replaying execution of the distributed Java programs, as described above. As an example, this method may be implemented in the particular hardware environment discussed above with regard to Figure 1.

Such a method may be implemented, for example, by operating the CPU 116 (Figure 1), to execute a sequence of machine-readable instructions. These instructions may reside in various types of signal-bearing media.

Thus, this aspect of the present invention is directed to a programmed product, comprising signal-bearing media tangibly embodying a program of machine-readable instructions executable by a digital data processor incorporating the CPU 2 and hardware above, to perform a method of recording and replaying execution of distributed Java programs.

This signal-bearing media may include, for example, RAM 114 contained externally or within the CPU 116, as represented by fast-access storage for example. Alternatively, the

instructions may be contained in another signal-bearing media, such as data storage 130 (Figure 1) or a magnetic data storage diskette 1300 (Figure 13), directly or indirectly accessible by the CPU 116.

Whether contained in the diskette 1300, the computer 100, or elsewhere, the instructions may be stored on a variety of machine-readable data storage media, such as DASD storage (e.g., a conventional "hard drive" or a RAID array), magnetic tape, electronic read-only memory (e.g., ROM, EPROM, or EEPROM), an optical storage device (e.g. CD-ROM, WORM, DVD, digital optical tape, etc.), paper "punch" cards, or other suitable signal-bearing media including transmission media such as digital and analog and communication links and wireless. In an illustrative embodiment of the invention, the machine-readable instructions may comprise software object code, compiled from a language such as "C", etc.

Thus, while the invention has been described in terms of preferred embodiments, those skilled in the art will recognize that the invention can be practiced with modification within the spirit and scope of the appended claims.